		STUDY MODULE D	ESCRIPTION FORM				
	f the module/subject	rical drives		Code 1010331151010330053			
Field of study Control Engineering and Robotics			Profile of study (general academic, practica (brak)	ıl)	Year /Semester		
	e path/specialty	-	Subject offered in: Polish		Course (compulsory, elective)		
Cycle o	f study:		Form of study (full-time,part-time	e)			
	First-cyc	ele studies	full-time				
No. of h	iours				No. of credits		
Lectu	014000	1	Project/seminars:	-	2		
Status of	ak)						
(brak) (b Education areas and fields of science and art					ECTS distribution (number and %)		
technical sciences					2 100%		
Responsible for subject / lecturer: dr hab. inż. Roman Muszyński							
tel. Fac	ail: Roman.Muszynski 061 665 2735 :ulty of Electrical Engir Piotrowo 3A 60-965 Po	eering					
Prere	equisites in term	s of knowledge, skills an	d social competencies	51			
1	Knowledge	Student should have knowledge in chosen branches of physics including the electricity and the magnetism and the knowledge of the theory of electric circuits.					
2	Skills	Student is able to obtain information from literature, databases and other sources; has abilities of the self-education for improving qualifications and the update of professional competence.					
3	Social competencies	Student is aware of a need to expand his competence and readiness to undertake the cooperation in the team; has an awareness of the importance and understands other aspects of engineering activity, including its influence on the environment.					
Assu	mptions and obj	ectives of the course:					
Gettin	g knowledge of buildir	ng, operation and characteristics o	f the basic drives with convert	ers.			
	Study outco	mes and reference to the	educational results fo	r a f	ield of study		
Knov	vledge:						
		dge tidied up in the structure, the	application and control of the	auto	mation and robotics systems		
 - [K_W19++] - [-] 2. Student knows and understands typical engineering technologies, knows and understands principles of the selection of servo- and measuring-testing devices [K_W20++] - [-] 							
Skills		, <u></u>					
 Student is able to use models of simple electromechanical systems, as well as to use them for analysis and design automations and robotics systems [K_U05+++] - [-] 							
2. Student is able to select the kind and parameters of servo- and measuring system, control unit for the chosen application and to effect their integration in the form of the ultimate measuring-control system [K_U17++] - [-]							
	al competencies:						
1. Student has an awareness of the need for the professional approach towards technical issues, of meticulous acquainting oneself with documentation and environmental conditions, in which devices and their elements can function - [K_K04++] - [-]							
	Assessment methods of study outcomes						

Laboratory exercises are attested on the base of presence at the laboratory, activity during exercising and report after it (one report for exercising group)

Course description

Parameters, characteristics and operation modes of the induction and DC machine, thyristor DC drive, methods of induction motor starting, frequency control of tha induction motor, thermal states of the electrical machine, fun drive.

Basic bibliography:

1. 1. Drozdowski P.: Wprowadzenie do napędów elektrycznych. Skrypt Politechniki Krakowskiej, Kraków 1998.

2. 2. Sidorowicz J. Napęd elektryczny i jego sterowanie. Oficyna Wydawnicza Politechniki Warszawskiej 1994

3. 3. Kaczmarek T.: Napęd elektryczny robotów, wyd.2, Wydawnictwo Politechniki Poznańskiej, Poznań 1998.

Additional bibliography:

1. 1. Muszyński R., Kaczmarek T.: Sterowanie układami elektromechanicznymi. Przykłady obliczeniowe. Wydawnictwo Politechniki Poznańskiej, Poznań 2007.

2. 2. Tunia H., Kaźmierkowski M.P.: Automatic Control of Converter-fed Drives, Elsevier Amsterdam ? London ? New York ? Tokyo, PWN Warszawa 1994.

3. 3. Dewan S. B., Slemon G. R., Straughen A.: Power Semiconductor Drives. John Wiley & Sons, New York, Chichester, Brisbane, Toronto, Singapore 1984.

Result of average student's workload

Activity		Time (working hours)
1. Participation in the exercises		15
2. Consultation		2
3. Preparation for exercises		13
4. Preparation of the reports	15	
Student's wo	rkload	
Source of workload	hours	ECTS
Total workload	45	2
Contact hours	17	2
Practical activities	0	0